

# A Sparse Grid DG method for the Vlasov-Poisson System

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+ fruitful & inspiring discussions: B. Makridakis & M. Georgoulis

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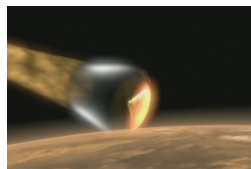
# Outline

- 1 Motivation & What's about
- 2 DG for Vlasov-Poisson system (1D)

# Motivation: Kinetic Equations

**Aim:** Description of “dilute particle gases” at an *intermediate* scale between microscopic scale and the hydrodynamical scale

- “Dilute gases”: Huge system of particles (each particle:  $x$  and  $v$ )
  - ▷ *Statistical Description*



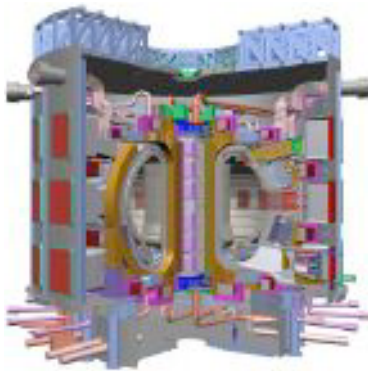
**Examples of “dilute gases”:** Plasma Physics (electrons, neutrons, ions), Astrophysics (galaxies, stars), Economy (individuals), Re-entry of aircraft: (gas molecules), ...

**Main object:**  $f(t, x, v)$

- ▷ gives “probability” of finding particles in volume  $dx dv$  at time  $t$ , around  $(x, v)$

# Motivation: Plasma & ITER-project

- **Fusion:** can we produce clean & huge energy?
- transport of charged particles in Plasmas



## Tokamak

(toroidal chamber with magnetic coils)

# Vlasov-Poisson system

## Mean field approximation

$$\begin{cases} \frac{\partial f}{\partial t} + v \cdot \nabla_x f + \nabla_x \Phi(t, x) \cdot \nabla_v f = 0 \\ -\Delta_x \Phi = \pm \rho \quad (-\operatorname{div}_x F = \pm \rho) \\ f(0, x, v) = f_0(x, v) \end{cases}$$

$$(x, v, t) \in \Omega_x \times \mathbb{R}^3 \times [0, T]$$

- **Electrostatic Vlasov-Poisson:** transport of charged particles in plasmas  $U(x) = -\frac{1}{4\pi} \frac{1}{|x|}$ .
  - **Gravitating Vlasov-Poisson :**  $U(x) = \frac{1}{4\pi} \frac{1}{|x|}$
  - **Vlasov-Maxwell:**  $F(t, x) = E(t, x) + \frac{v}{c} \wedge B(t, x)$
- **Remark:** Real Simulation require solving **3D VP-VM (6 +1 dimensional)!!**

# 1D Vlasov-Poisson System

$$\begin{aligned} \frac{\partial f}{\partial t} + v \frac{\partial f}{\partial x} - \Phi_x f_v &= 0 & (x, v) \in [0, 1] \times [-L, L], t \in [0, T], \\ -\Phi_{xx} &= \rho(x, t) - 1 & (x, t) \in [0, 1] \times [0, T], \end{aligned}$$

+ initial condition  $f(x, v, 0) = f_0 \geq 0$  +bc: periodic in  $x$

- [Cooper-Klimax (80)]:  $\exists L > 0$  :  $f(x, v, t) \equiv 0$  for all  $v \notin [-L, L]$

$$\rho(x, t) := \int_{[-L, L]} f(x, v, t) dv \quad : \quad \int_0^1 \rho(x, t) dx = 1$$

$$\boxed{\Omega = [0, 1] \times [-L, L]} \quad \Omega_t = \Omega \times [0, t]$$

- Existence, Uniqueness & Regularity: ✓

[Jordanski (64), Cooper-Klimax (80), Glassey (96), ...]

# Properties of Vlasov-Poisson System

- $f = f(x, v, t)$ ,
- $E := \Phi_x = \Phi_x(x, t)$

$$(VP-1D) \quad \begin{cases} \bullet \frac{\partial f}{\partial t} + v \frac{\partial f}{\partial x} - E f_v = 0 & \text{in } \Omega_t, \\ \bullet -\Phi_{xx} = \rho - 1 & \text{in } [0, 1] \times [0, T], \end{cases}$$

- **Positivity**  $f(x, v, t) \geq 0$ ,  $\forall x, v, t$
- **mass conservation:**  $\int_{\Omega} f(x, v, t) dx dv = 1$ ,  $\forall t$   $[\int_0^1 \rho dx = 1]$
- **$L^p$ -conservation:**  $\|f(t)\|_{L^p(\Omega)} = \|f(0)\|_{L^p(\Omega)}$ ,  $1 \leq p \leq \infty$ .
- **Energy conservation:**  $\frac{d}{dt} (\int_{\Omega} f(x, v, t) |v|^2 dx dv + \int_{\mathcal{I}} [E(x, t)]^2 dx) = 0$

- **Remark:** A Good Numerical scheme should *enjoy* these properties

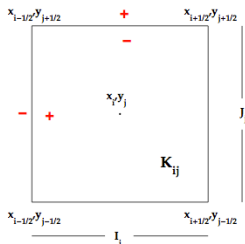
# Numerical Simulation - Approximation for VP

- **Particle Methods:** [Cottet & Raviart (84), Birdsall&Langdon (85),...]
    - **PIC** (and related) methods *noise in phase space*
  - **Eulerian Methods:**
    - **Finite Volumes (FV):** [Filbet (2001),Crouseilles & Filbet (2004)]
      - *low order, restrictions on the mesh, ...*
    - **Semi-Lagrangian Methods:** [Sonnendrücker et. al (98-...), Besse (08-09)..]
      - *need of high order interpolation for origin of characteristic*  
→ *loss of local character of reconstruction, ..., expensive*
    - **Discontinuous Galerkin:**
      - **Simulation:** [Gamba et al(12), Rossmannith& Seal (12), BA&Hajian(...)]
      - **Analysis:** [B.A, Carrillo & Shu (11) & (12)]
- **Our Aim:** Tackle high dimensionality (if possible within DG)



# Basic Notation

- Partition  $\mathcal{I}_h = \{I_i\}_{1 \leq i \leq N_x}$  of  $\mathcal{I} = (0, 1)$  with  $I_i = (x_{i-1/2}, x_{i+1/2})$   
 $\mathcal{J}_h = \{J_j\}_{1 \leq j \leq N_y}$  of  $\mathcal{J} = (-L, L)$  with  $J_j = (y_{j-1/2}, y_{j+1/2})$
- $\mathcal{T}_h = \mathcal{I}_h \otimes \mathcal{J}_h$  cartesian partition of  $\Omega$  into elements  $K$
- $\mathcal{Z}_h^k := \mathbb{Q}^k(\mathcal{T}_h)$



- Traces:**  $(\phi_h)_{i+1/2, v}^{\pm} := \phi_h(x_{i+1/2}^{\pm}, v)$ ,  $(\phi_h)_{x, j+1/2}^{\pm} := \phi_h(x, y_{j+1/2}^{\pm})$
- Average :**  $\{\phi_h\}_{i+1/2, v} := \frac{1}{2}((\phi_h)_{i+1/2, v}^{+} + (\phi_h)_{i+1/2, v}^{-})$
- Jump:**  $[[\phi_h]]_{i+1/2, v} := (\phi_h)_{i+1/2, v}^{+} - (\phi_h)_{i+1/2, v}^{-}$